Air quality monitoring from global to local scales

Applications of satellites and microsensors – examples of two rapidly evolving technologies

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1. Satellite-based air quality monitoring

Can satellite observations of atmospheric composition help with air quality monitoring?

2. Low-cost microsensors for air quality mapping

Given the current state of sensor technology, how can we best exploit low-cost microsensors for urban-scale air quality mapping?



PART 1: SATELLITE MONITORING



Why the view from space?

- Spatially exhaustive information
- Global data availability
- Consistent and
 - homogeneous time series of data
- Archive of several decades of worldwide data

Satellite-based air quality monitoring

- Technically not that "new"... has been around since mid-1990s
- However: So far mostly used for global and regional applications due to coarse spatial resolution
- Only now are instruments slowly becoming suitable for (slightly) more detailed observations of urban air quality



Aerosol Optical Depth



Particulate Matter





Global satellite-derived map of $PM_{2.5}$ averaged over 2001-2006. MODIS and MISR AOD was used. From: Van Donkelaar et al. 2010.



Relationship between AOD and station $PM_{2.5}$ (left panel) and satellite-mapped PM2.5 in the Stockholm area (right panel). From Glantz et al. (2009)



Sulphur dioxide (SO₂)



AIRS-derived regional scale SO₂ plume from Nyamuragira volcano, 28 Nov to 3 Dec 2006. From Prata and Bernardo (2007)



 SO_2 plume of the eruption of the Eyjafjallajökull volcano, Iceland, May 2010.

OMI SO2 VCD [DU] 2005-2013



SO₂ hotspot over the Svanvik/Nikel area on the Norway/Russia border, based on OMI data (K. Stebel/N. Theys).

SO₂ (milli atm-cm)

Nitrogen Dioxide (NO₂)

Tropospheric NO2 column average 2004-2016 [in 10e15 molec. cm^2]



Long-term average tropospheric NO2 column as measured by the OMI instrument onboard of the Aura platform. Units in 10¹⁵ molecules per cm².

Temporal evolution



Time series of tropospheric NO₂ over China

Note on measurement uncertainty

The average relative uncertainty of individual (daily) satellite observations of NO_2 is approximately 30%. This random error is reduced significantly when multiple measurements are averaged over time (e.g. monthly averages)



Satellite based annual average NO2 by region





OMI-based estimate of relative change (in percent of long-term average) of nitrogen dioxide (NO₂) between 2004 and 2016. (Schneider et al., 2015, ACP)



Tropospheric NO2 column average 2004-2016 [in 10e15 molec. cm^2]



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New opportunities: TROPOMI

- TROPOMI is an instrument on the upcoming Sentinel-5P mission
- Launch in June 2017
- Spatial resolution of 7x7 km²
- Products for NO₂, O₃, SO₂, CO, HCHO, CH₄, and Aerosols





A comparison of the footprint of TROPOMI (nadir pixel) to past and current air quality satellite instruments

Airborne NO₂ mapping with the APEX instrument









PART 2: LOW-COST MICROSENSORS



Traditional Air Quality Monitoring

- Large
 Complex
 High-maintenance
 - Expensive
 - \rightarrow Very sparse

AND 640

Is there another way?

There might be...





















Red markers: Locations of Air Quality Monitoring stations for NO₂ Blue markers: Deployment sites of low-cost microsensors

Combination with model output

- To map the observations from the low-cost sensors onto a high-resolution grid in a scientifically meaningful way we need to use a spatial auxiliary dataset that guides the interpolation
- We use here the output from the EPISODE air quality model (highresolution long-term average concentration maps)



Annual average concentration of NO2 for 2014 as compute by the EPISODE air quality model.





Data fusion (as a subset of data assimilation) creates a value-added product by

- a) Interpolating the observations in an objective way
- b) "correcting" the model estimates with true observations





Data fusion method used here provides a combined concentration field by separately interpolating the observational residuals from a regression model and then combining both.





AQMesh nodes

 $\mu g/m^3$.

(markers). Units in

Oslo NO₂ modelderived annual average basemap (background) and observations from AQMesh nodes (markers) on 6 January 2016 at 9:00 UTC. Units in $\mu g/m^3$.

Note: The sensors used here were all co-located for several weeks at the Kirkeveien AQ monitoring station before deployment and are thus fieldcalibrated!

Data fusion result [ug/m3]









Example of a data fusion-based surface concentration field of NO₂ for Oslo, Norway, at 100 m spatial resolution (link).









Example of a data fusion-based surface concentration field of NO_2 for Barcelona, Spain, at 100 m spatial resolution (<u>link</u>).



Example of 24 hours of data fusion results in Oslo, combining NO₂ measurements from the AQMesh units with a longterm average basemap derived from the EPISODE model, here shown

for 6 January 2016

0000UTC







Data fusion maps: Daily cycle of NO₂, PM₁₀, and PM_{2.5} for Oslo on January 6 2016 (NO2) and 22 March 2016 (PM).

Comparison to AQ monitoring stations





Entire daily cycle of NO_2 as measured by the reference air quality monitoring stations versus the NO_2 concentrations provided by the data fusion map.



Black line: Reference AQM stations

Red line: Data fusion of AQMesh low-cost sensor network and EPISODE



Field calibration of the sensors is crucial!

Without field calibration







Dependency of map quality on network size



Take-home messages

There are currently two exciting developments regarding new monitoring techniques:

1. Higher-resolution satellite data for AQ monitoring

Satellite observations of air quality, which so far are mostly useful for global and regional applications are finally reaching a spatial resolution that make them somewhat usable for (limited) urbanscale applications

2. Low-cost microsensors for AQ monitoring

Despite many challenges at the individual sensor level, low-cost microsensors allow for detailed high-resolution urban-scale mapping of air quality if several conditions are met:

- a) the "swarm knowledge" of the entire network is used
- b) the sensor observations are combined with output from an air quality model

c) the sensors are calibrated in the field



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Thank you for your attention!

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